

RODON®

Tolerance Based Simulation & Automated FMEA
generation in Aircraft
Elevators

4th Annual Systems Engineering Conference
Dallas, October 22 - 25, 2001

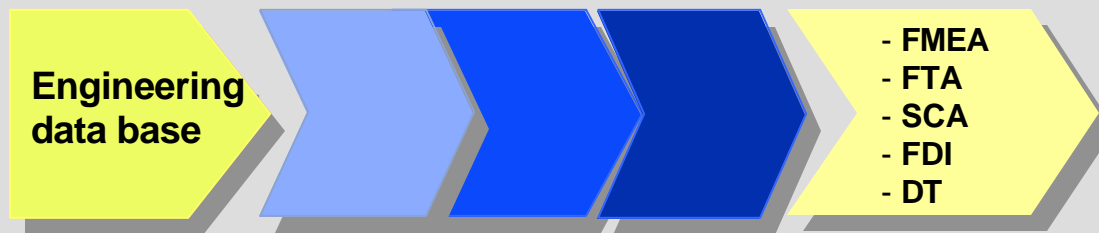


How to improve supportability, affordable readiness & RTOC ?

Our basic approach:

- **Seamless math-based data flow** from Engineering data to FMEA and Service

Information



This leads to:

- **Reduced costs**

- Lower development costs for FMEA & Service Information (FDI) generation

- **Improved Quality**

- More complete and accurate FMEAs & Troubleshooting Procedures

- **Reduced Lead times**

- Design validation early on in the development process
 - Early Availability of Service Information (FDI)



How can a math- based seamless data flow be achieved?

By using a software tool which allows

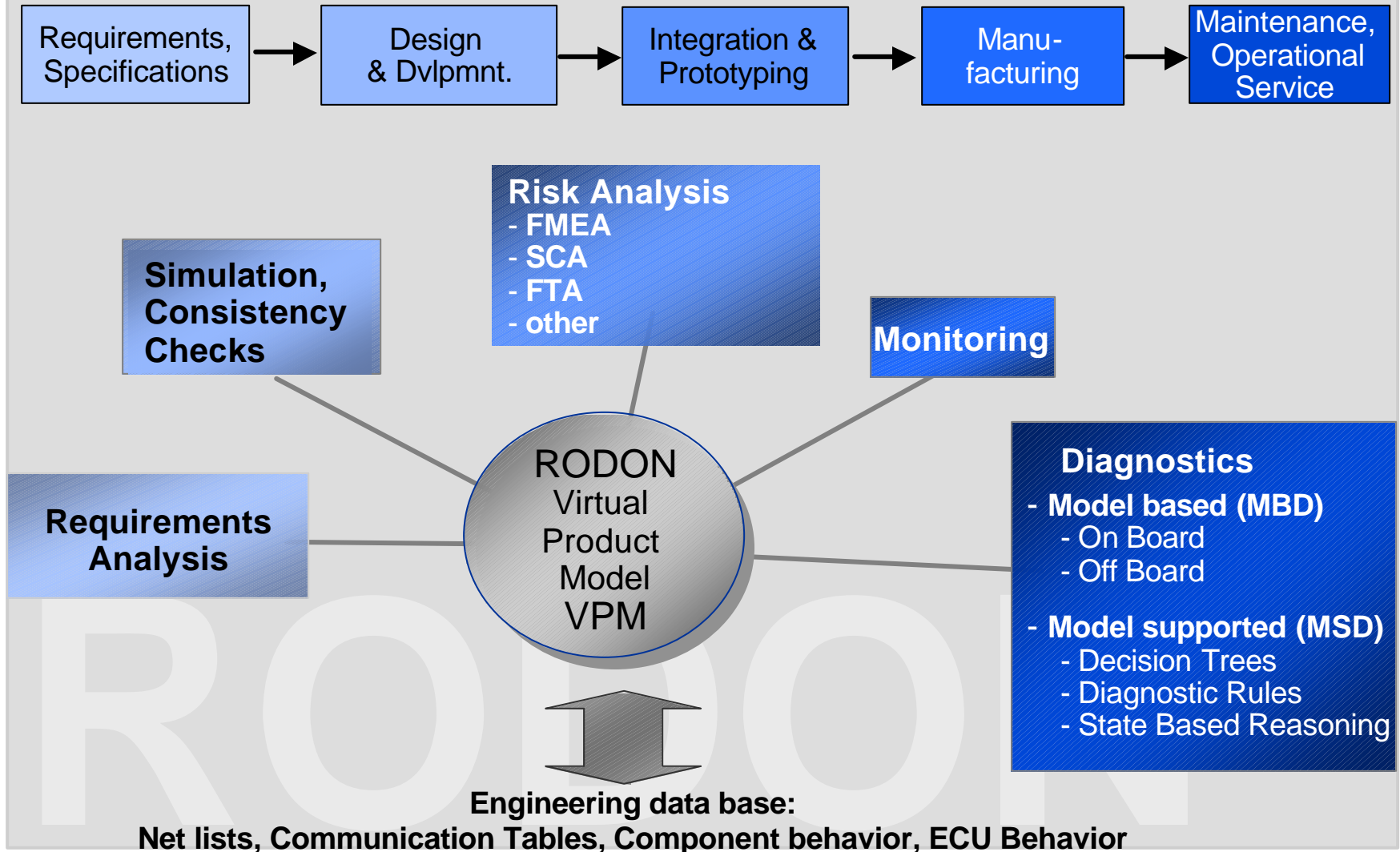
- To create a simulation model of a system based on its
 - Functional behavior
- To have analysis capabilities available for
 - Validation of functional design & Risk analysis
 - Diagnostics (FDI)
 - Non-functional attributes
 - like cost, mass for early on requirements analyses
 - Failure probability on component level for FTA

=> Both requirements are fulfilled by the model-based software tool **RODON**



RODON - Application Areas

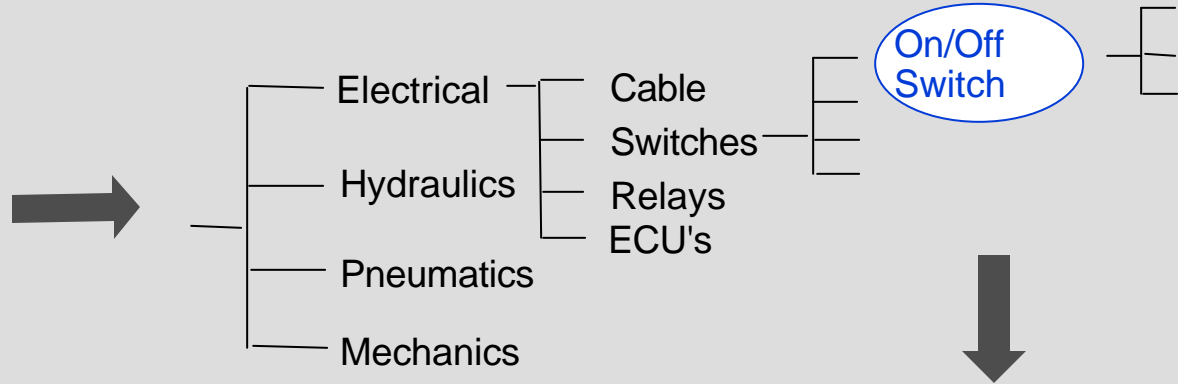
RODON is a Software-Tool for System Integration based on the analysis of the functional behavior of the components





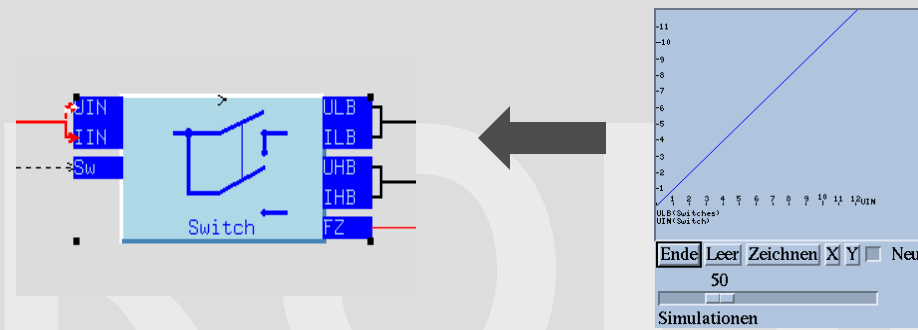
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Modeling I - Components



Model Description - Transfer Functions

Model Visualization



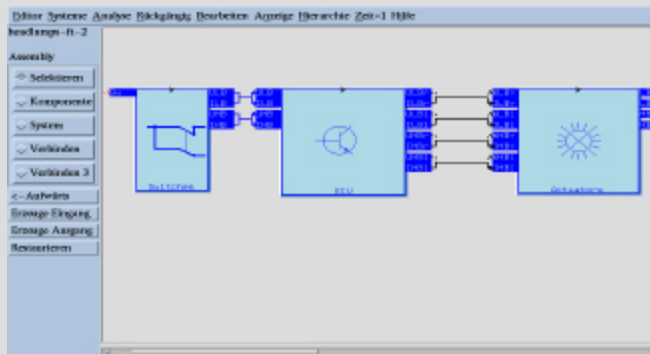


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Modeling II - Connectivity, Assemblies and Systems

Connectivity on Component and Assembly Level

Modeling I
→



Execution of Analyses

Rqmts Analysis

Simulation

Risk Analysis

Monitoring

Diagnosis

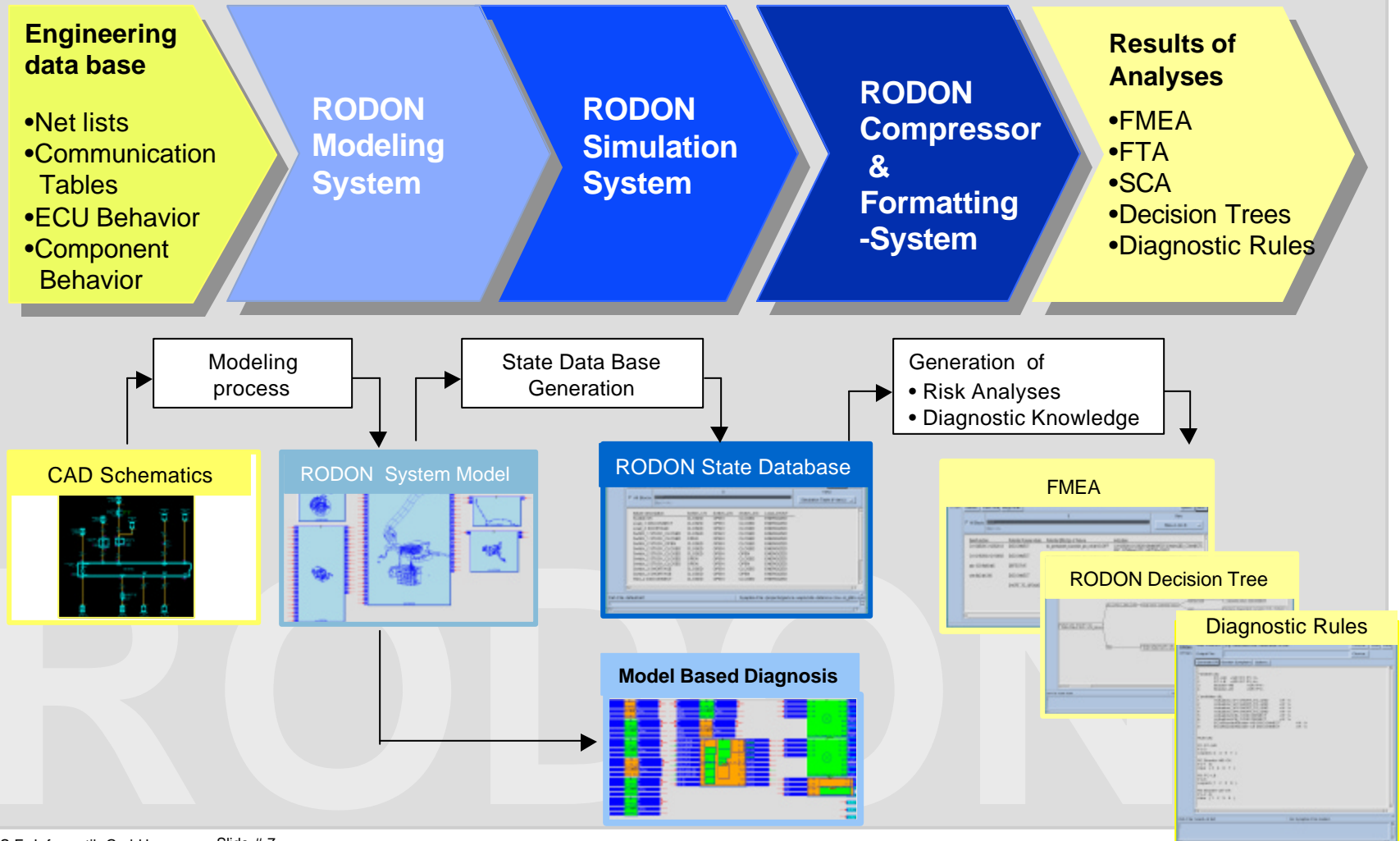
Highlights & Features:

- Description of **Nominal Behavior**
- Hierarchical Model Structure based upon BOM
- **Multidirectional Determination** of all Values of the System
- Qualitative and quantitative Values
- Representation of **Tolerances** as Intervals
- Steady State and Dynamic Analyses
- **Top-Down** and **Bottom-Up** Approach
- Definition of **Failure Modes** on Component Level
- Straight Forward Variant Handling



The RODON Process

- Generates Models Automatically from Design Data
- Generates all Analyses by calculation from one Model



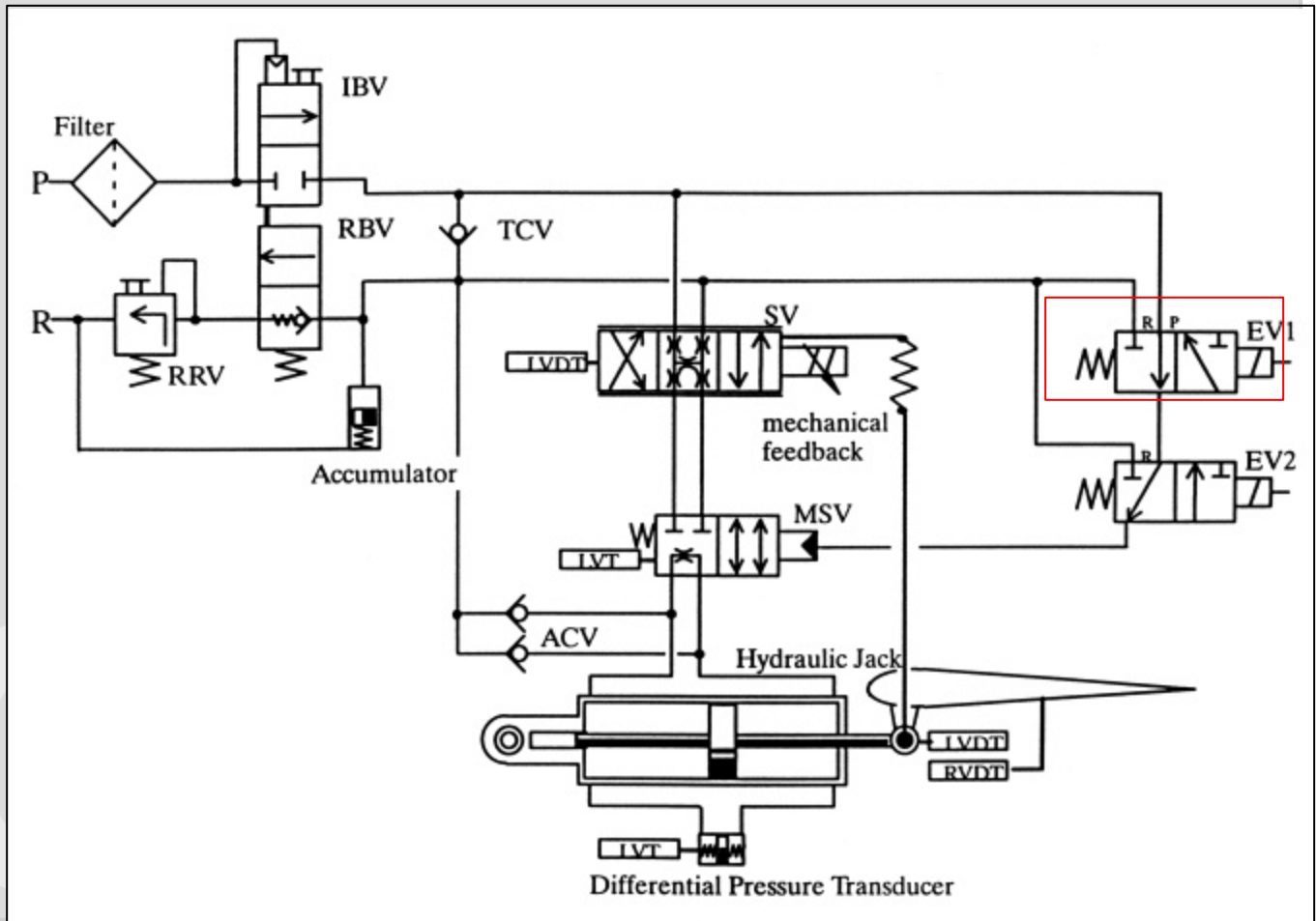


Example: Project with Aircraft Manufacturer

Aircraft Elevator - Fly by wire system

System consists of:

- **Hydraulic** control loop
- **Controller Logic**
- **Electrical** Wiring





Example: Aircraft Elevator - Fly by wire system

Tasks:

- Simulate maximum deviation of actual value from set point depending on tolerances & offsets of inputs
- Investigate impact of tolerances & offsets on behavior of monitors
- Investigate impact of failure modes on behavior of monitors

Methodology:

- Create RODON Virtual Product Model
- Simulation with Tolerances for time-dependent systems
- Failure-Mode-Simulations for time-dependent systems

Additional benefits concurrently to the simulations:

- Automated FMEA generation for dynamic systems
- Generation of Troubleshooting Procedures

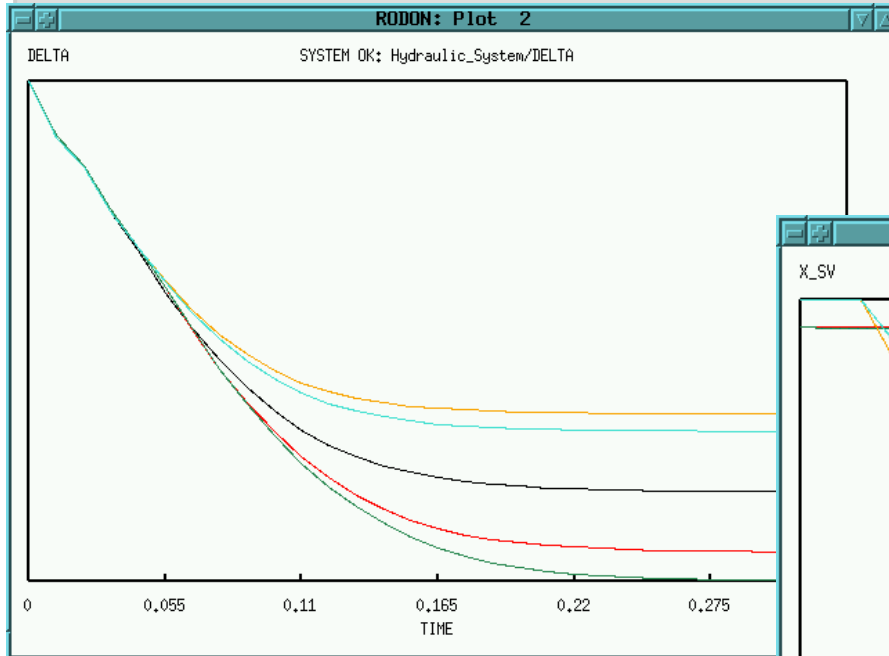




Example: Aircraft Elevator - Fly by wire system

Tolerance-Simulations with RODON

- Sensor-tolerances
- Offsets



Elevator position versus time after stimulation with a step function.

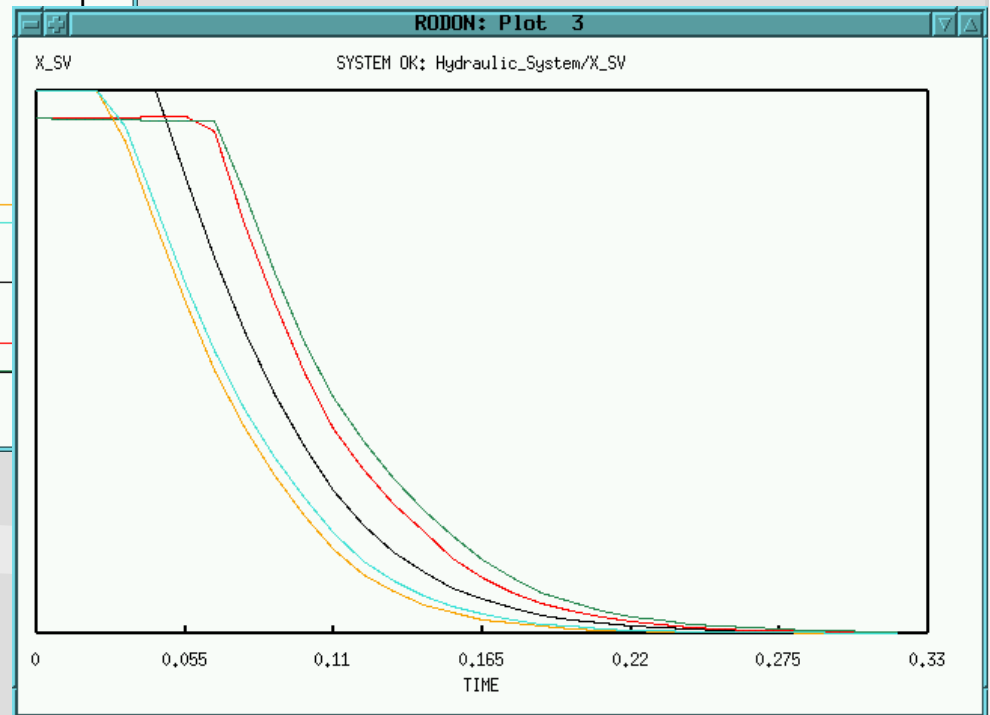
Black: no offsets & tolerances

Yellow / cyan:

upper boundary of tolerances & offsets

Red / green:

lower boundary of offsets and tolerances

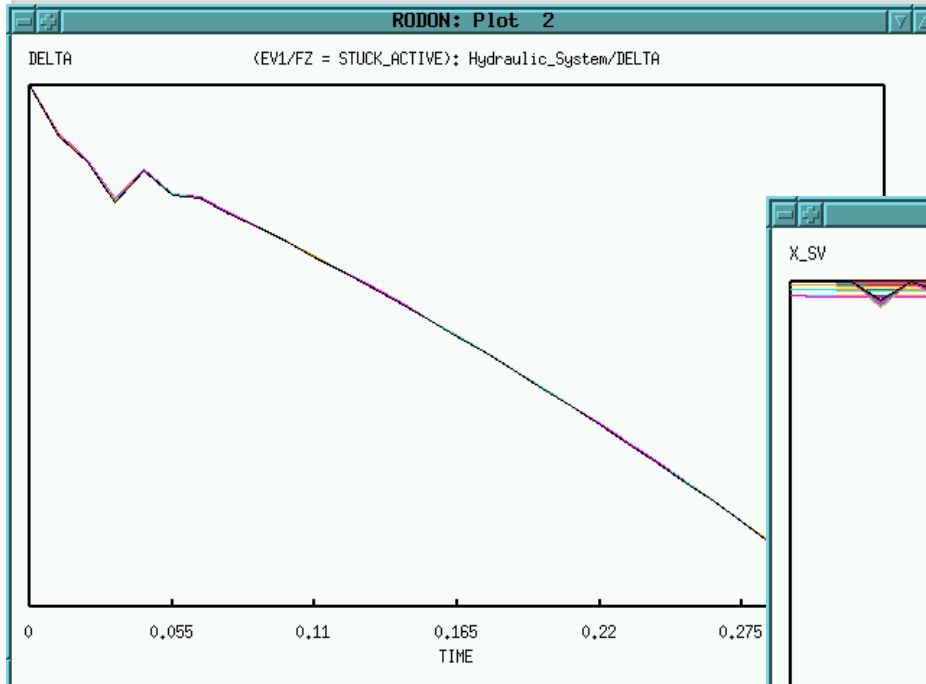


Servo-valve position versus time, controlling the elevator position.



Example: Aircraft Elevator - Fly by wire system

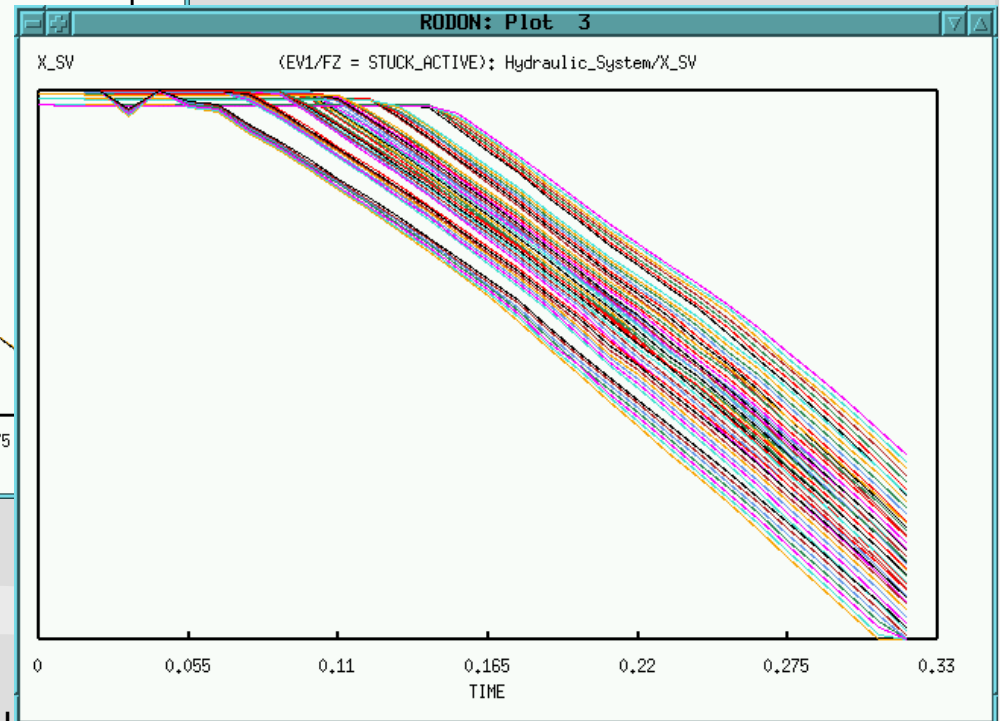
Failure Mode Simulations



Elevator position versus time. „Run-away“ situation.

Failure-mode is Enabling Valve EV1 „STUCK_ACTIVE“.

Effect: Main Servo Valve is closed; no control possible. Elevator runs away due to air loads.

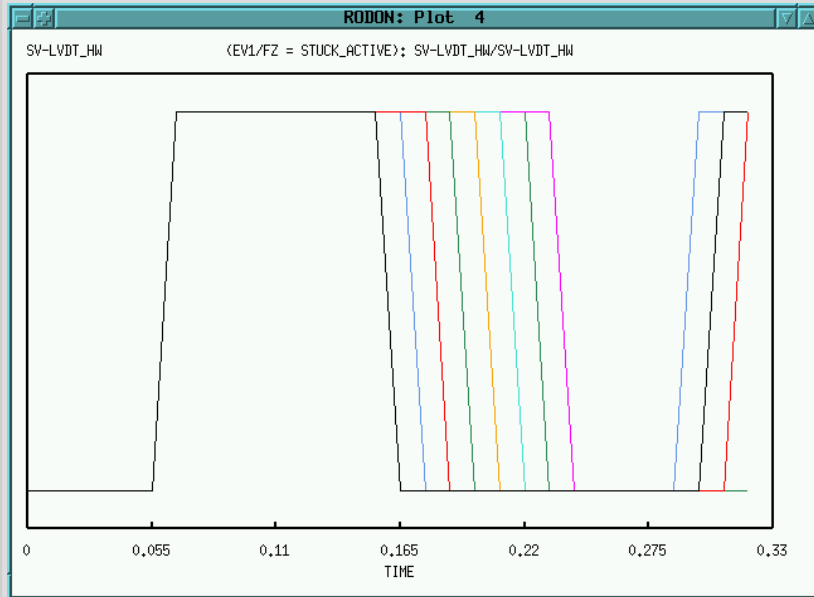


Servo Valve position versus time for all offsets and tolerances. Position of Servo Valve has no influence on elevator due to closed Main Servo Valve.

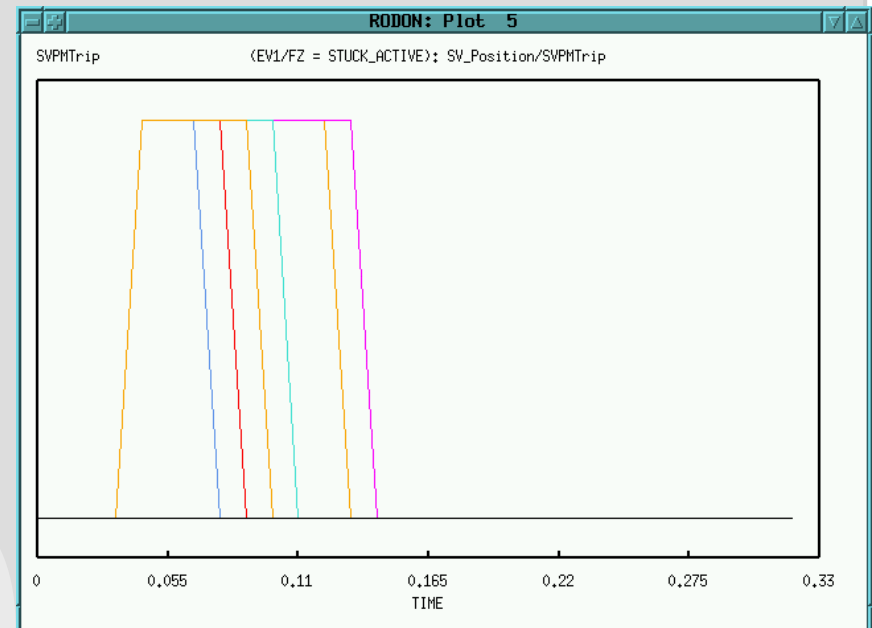


Example: Aircraft Elevator - Fly by wire system

Excitation of Monitors



Sensor-Monitoring of sensor LVDT of Servo Valve SV. Monitoring behavior as expected.



Position-Monitoring of Servo Valve SV.
Monitor activated due to offsets and tolerances.
Unexpected Monitoring behavior!



Example: Aircraft Elevator - Fly by wire system

Results of the analysis

- Maximum deviation of actual value from set point due to the offsets and tolerances were larger than specified
- Offsets & Tolerances have significant impact on Monitoring for both
 - the nominal behavior mode
 - failure modes

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Example: Aircraft Elevator - Fly by wire system

Additional benefits - FMEA

The screenshot shows the RODON-SDB software interface. The main window displays a table of FMEA results. The table has four columns: Item/Function, Potential Failure Mode, Potential Effect(s) of Failure, and Indication. The table lists several failure modes for different components of the aircraft elevator system, including disconnects, stuck active, and short to ground. The interface also includes a menu bar (Datei, Einstellungen, Information, Extras, Hilfe), a toolbar with buttons like 'AutoSim...', 'Check SDB', 'Merge SDBs...', 'Options...', and 'Save...', and a status bar at the bottom indicating 'Def-File: Tiny.def' and 'No Symptom File loaded'.

Item/Function	Potential Failure Mode	Potential Effect(s) of Failure	Indication
ACT-LVDT	DISCONNECT	ACT-LVDT_HW/LVDT_HW=ON, Hydraulic_System/DELTA=-6.55, Hydraulic_System/X_SV=0.37, Hydraulic_System/X_ZYL=8.64, SV-LVDT_HW/SV-LVDT_HW=ON, SV_Position/SVPMTrip=ON	ACT-LVDT-Decoding/F=NO_LOAD/_GND_CON, Monitoring/LVDT_HW=ON, Monitoring/SV-LVDT-HW=ON, Monitoring/SVPM=ON
ACT-RVDT	DISCONNECT	ACT-RVDT_HW/RVDT_HW=ON	ACT-RVDT-Decoding/F=NO_LOAD/_GND_CON, Monitoring/RVDT_HW=ON
EV1	STUCK_ACTIVE	Hydraulic_System/DELTA=-3.19, Hydraulic_System/MSV=0, Hydraulic_System/X_SV=0.31, Hydraulic_System/X_ZYL=4.3, SV-LVDT_HW/SV-LVDT_HW=ON	Monitoring/SV-LVDT-HW=ON
LVDT_Exc_C_H	DISCONNECT	ACT-LVDT_HW/LVDT_HW=ON, Hydraulic_System/DELTA=-6.55, Hydraulic_System/X_SV=0.37, Hydraulic_System/X_ZYL=8.64, SV-LVDT_HW/SV-LVDT_HW=ON, SV_Position/SVPMTrip=ON	ACT-LVDT-Decoding/F=NO_LOAD/_GND_CON, LVDT_Exc_C_H/M_CONT=+, Monitoring/LVDT_HW=ON, Monitoring/SV-LVDT-HW=ON, Monitoring/SVPM=ON
	SHORT_TO_GND	ACT-LVDT_HW/LVDT_HW=ON, Hydraulic_System/DELTA=-6.55, Hydraulic_System/X_SV=0.37, Hydraulic_System/X_ZYL=8.64, SV-LVDT_HW/SV-LVDT_HW=ON, SV_Position/SVPMTrip=ON	ACT-LVDT-Decoding/F=NO_LOAD/_GND_CON, Monitoring/LVDT_HW=ON, Monitoring/SV-LVDT-HW=ON, Monitoring/SVPM=ON
RVDT_Act_V1	DISCONNECT	ACT-RVDT_HW/RVDT_HW=ON, Sensor_Integrity/SIMTrip=ON	ACT-RVDT-Decoding/F=NO_LOAD/_GND_CON, Monitoring/RVDT_HW=ON, Monitoring/SIMTrip=ON, RVDT_Act_V1/M_CONT=+
	SHORT_TO_GND	ACT-RVDT_HW/RVDT_HW=ON, Sensor_Integrity/SIMTrip=ON	ACT-RVDT-Decoding/F=NO_LOAD/_GND_CON, Monitoring/RVDT_HW=ON, Monitoring/SIMTrip=ON
SV-LVDT	DISCONNECT	SV-LVDT_HW/SV-LVDT_HW=ON	Monitoring/SV-LVDT-HW=ON, SV-LVDT-Decoding/F=NO_LOAD/_GND_CON
SV_Cmd_Minus	DISCONNECT	Hydraulic_System/DELTA=0, Hydraulic_System/X_SV=0, Hydraulic_System/X_ZYL=0,	Monitoring/SVPM=ON, SV_Cmd_Minus/M_CONT=+

System **FMEA** for **dynamic- and tolerance-** based systems; generated automatically out of the same RODON Virtual Product Model.

FMEA was used to **check** the **controller's self diagnostics** and **monitors** for about 300 failure modes.

Potential Effects:

- Observable and measurable variables of the hydraulic system

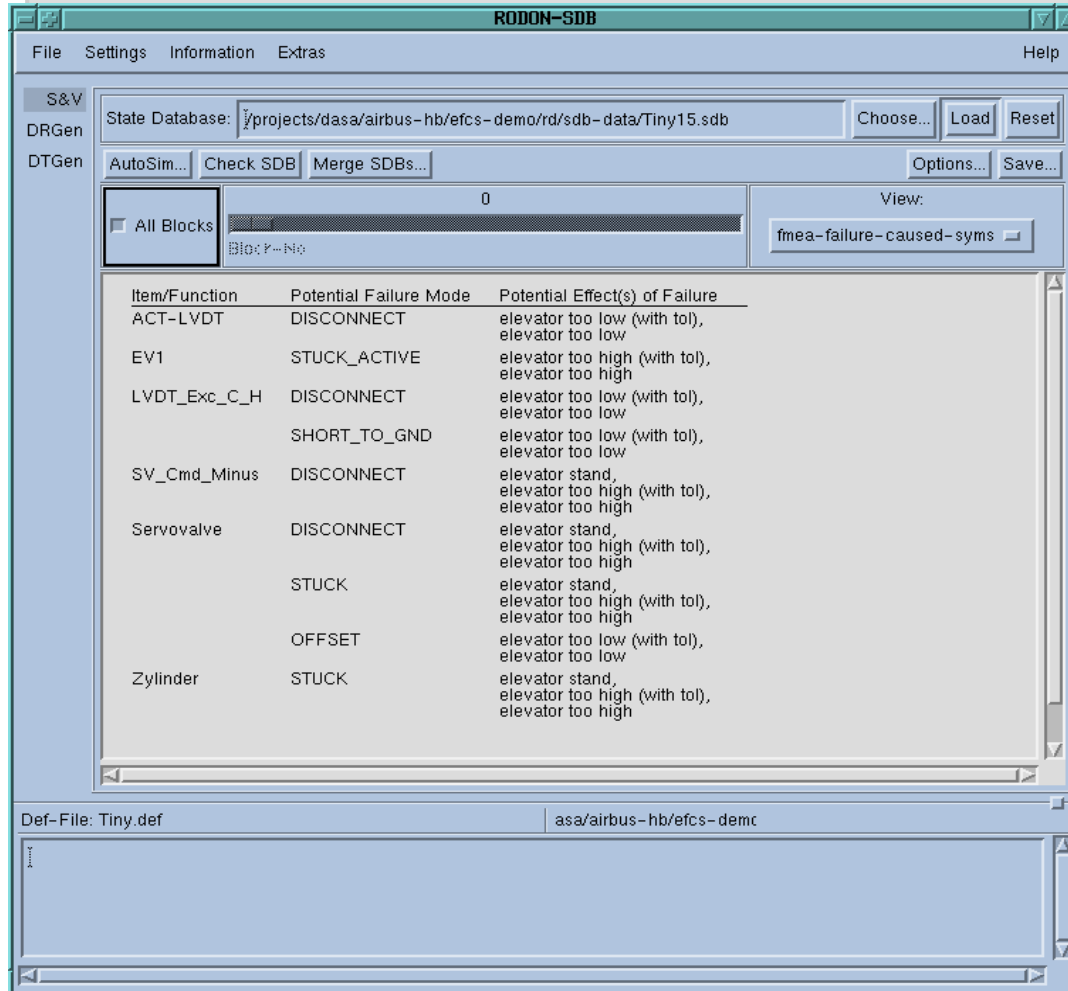
Indications:

- Monitors
- Diagnostic Trouble Codes



Example: Aircraft Elevator - Fly by wire system

Additional benefits - Simplified Fault Trees



Simplified Fault Trees:

Symptom -> possible causes relationship

Selected Symptoms

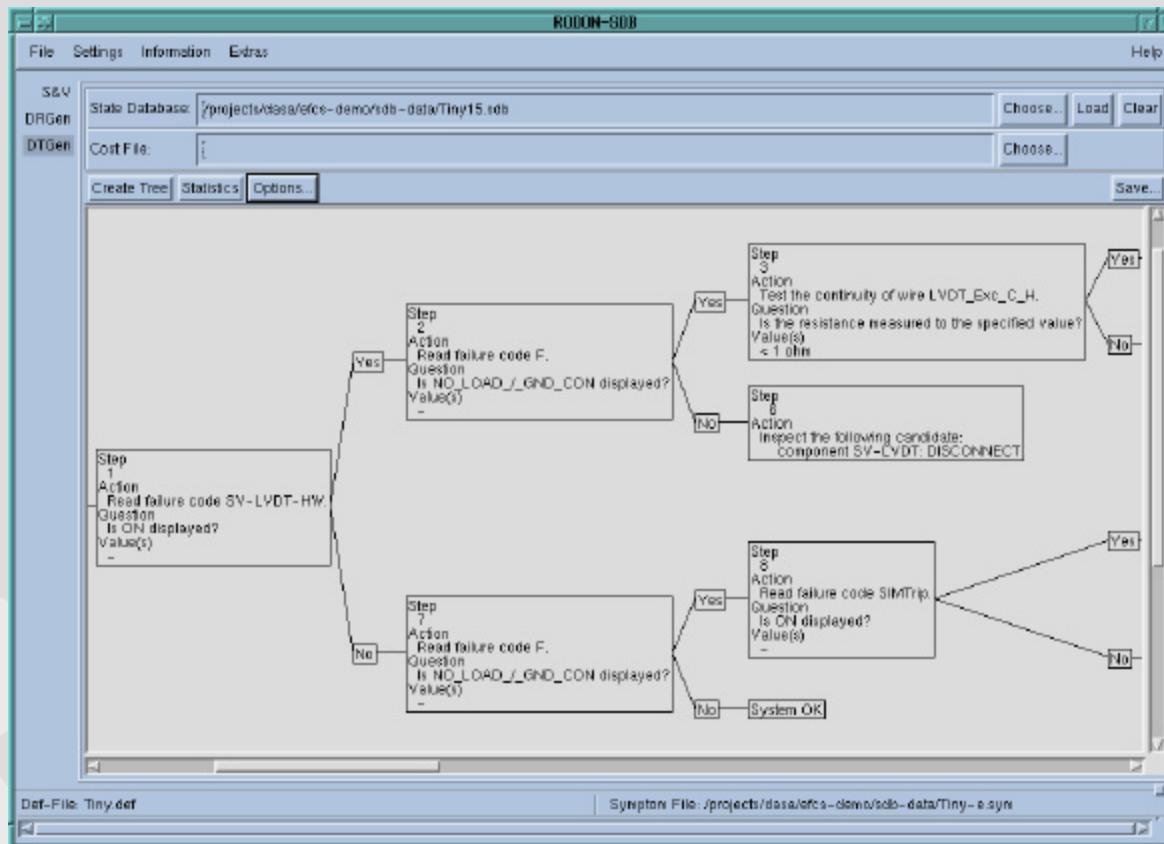
- Elevator too high
- Elevator too low
- Elevator stuck



Example: Aircraft Elevator - Fly by wire system

Additional benefits - Troubleshooting Procedures

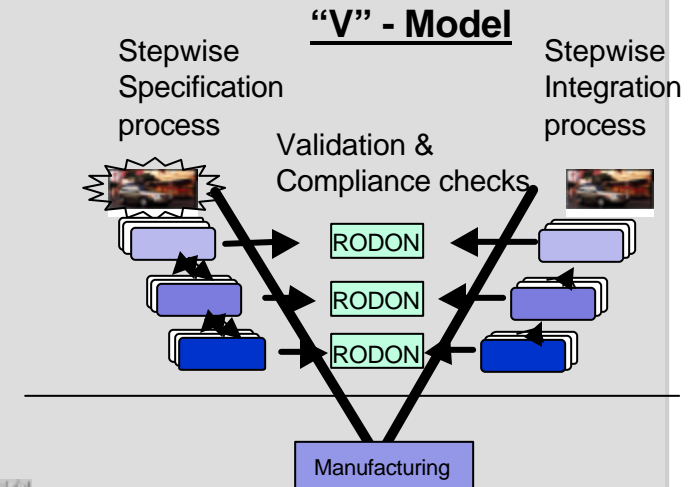
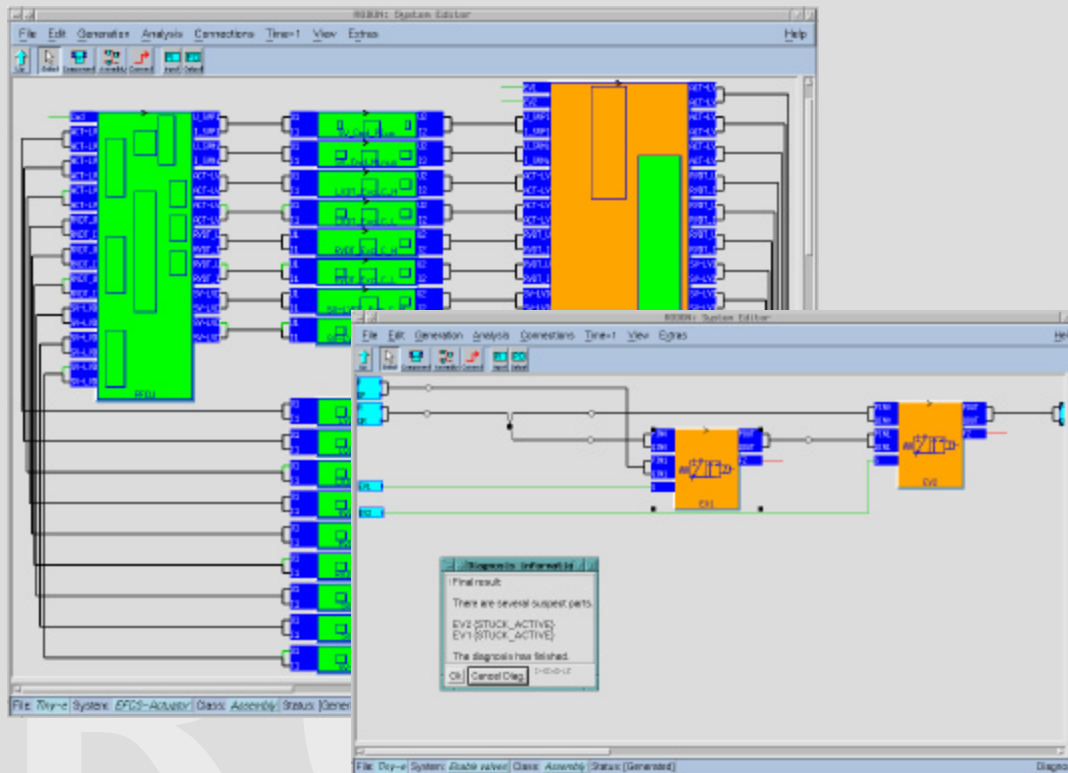
Automated generation of Troubleshooting Procedures (Decision Trees) out of the same RODON Virtual Product Model.





Additional benefit - Compliance checks for integration and test phases

Compliance checks between specifications and the real, physical system according to the “V”-Model can be performed by using RODON’s Model-Based Diagnosis (MBD) - Function.





Summary I

RODON-Support to Product Design, Integration & Maintenance

RODON supports the following tasks using the same RODON Virtual Product Model:

- Analysis of the design
- Automated Risk Analysis: FMEA, simplified FTA, Sneak Circuit Analysis (SCA)
- Automated generation of troubleshooting procedures and diagnostic rules
- FDI analysis of the design
- Coverage analysis in the design stage
- Subsystems' integratability tests by Virtual Prototyping
- Identification of fault conditions for ECU
- "Executable" FMEA with Math Based Model



Summary II

Benefits

- Reduces Effort

- To generate FMEA, FTA and diagnostic Information
- Creates “**Technical Memory**” over successive programs

- Improves Quality:

- More complete and accurate results
by using math based process

- Reduces lead times by early analysis of design

- Getting Errors out Early

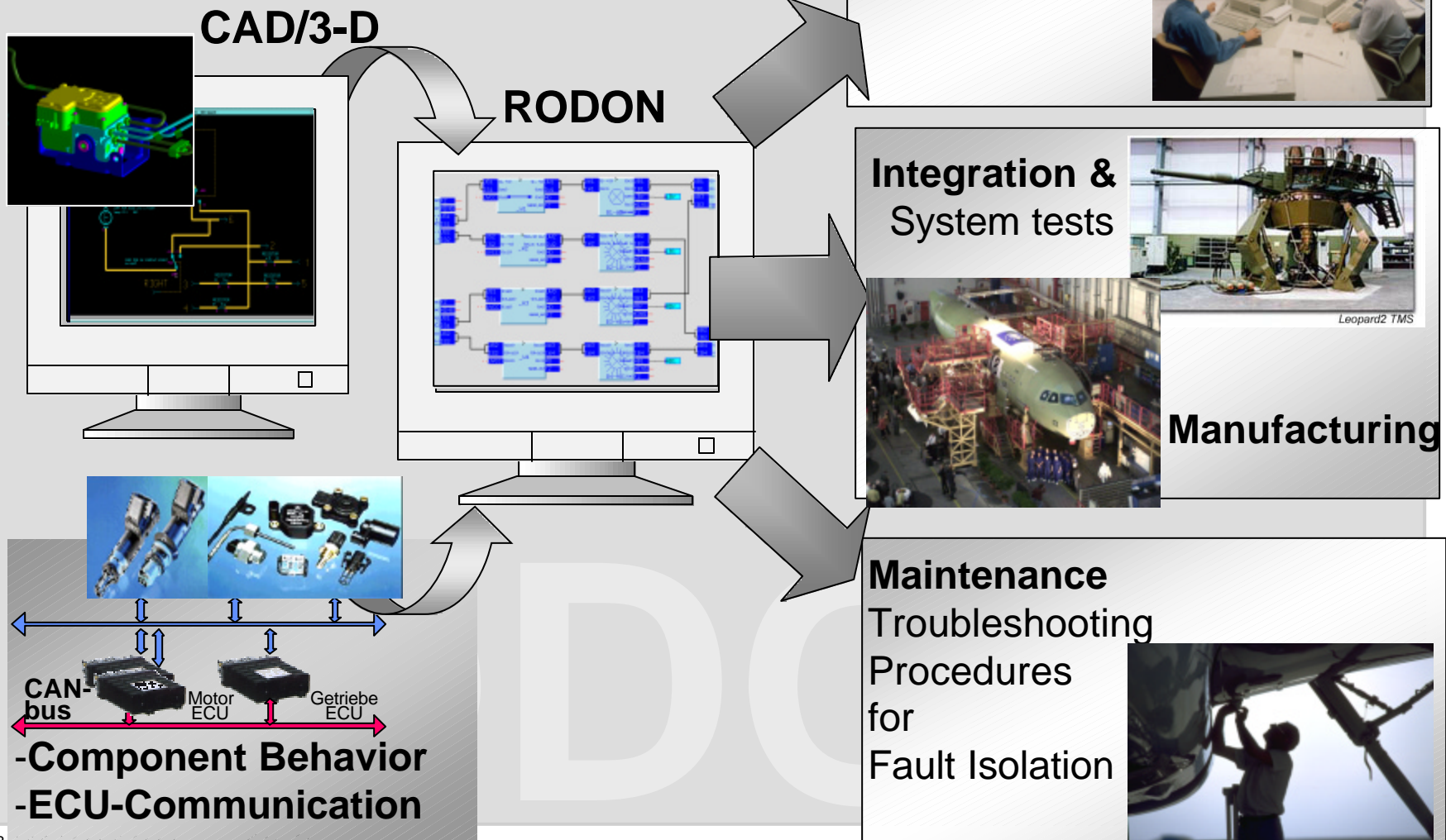
- Early Availability:

Diagnostic Information available at Integration & Test phase



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Overall Applications





R.O.S.E. Informatik GmbH

Major Customers

Automotive Industry

- General Motors (GM)
- DaimlerChrysler
- Volkswagen



Aerospace Industry

- NASA Ames Research Center
- EADS Airbus
- ASTRIUM Space Infrastructure



Military

- Krauss-Maffei Wegmann





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Exhibition Booth #

Contact Address:

Dr. Dirk Burow

RIG TEK, Inc.

Phone: (248) - 209 - 4585

Fax: (248) - 209 - 4505

e-mail: dburow@roseinformatik.com